



# Earth-Based Analogs & Modeling for Exercise Biomechanics in Space Dec. 12<sup>th</sup>, 2018

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Johnson Space Center  
& University of South Florida





- **University Collaboration**
- **Digital Astronaut Simulation**
- **Experimental Study**
- **Results & Takeaways**
- **Next Steps**





# University Collaboration

## Digital Astronaut Simulation

### Experimental Study

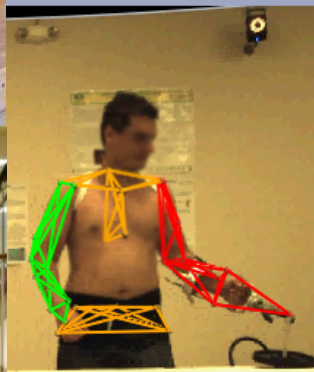
### Results & Takeaways

### Next Steps





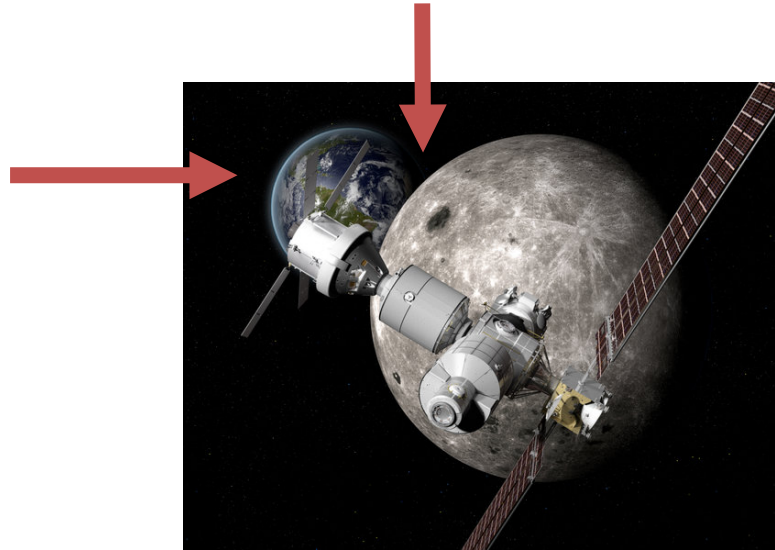
# Center for Assistive, Rehabilitation & Robotics Technologies (CARRT) @ USF




Human-Robot  
Interaction

Performance & Physical Rehabilitation

# NASA Space Technology Research Fellowship (NSTRF17)





The background of the slide is a composite space image. On the left, a large, grey, cratered celestial body (likely an asteroid or part of the Moon) is visible. In the upper center, a small satellite with a yellow antenna and solar panels is shown. In the upper right, the reddish-orange planet Mars is visible. On the right side, the large, grey, cratered Moon is shown. In the bottom right corner, the International Space Station (ISS) is visible in orbit above the blue and white horizon of the Earth. A faint white grid is overlaid on the entire background.

# **University Collaboration**

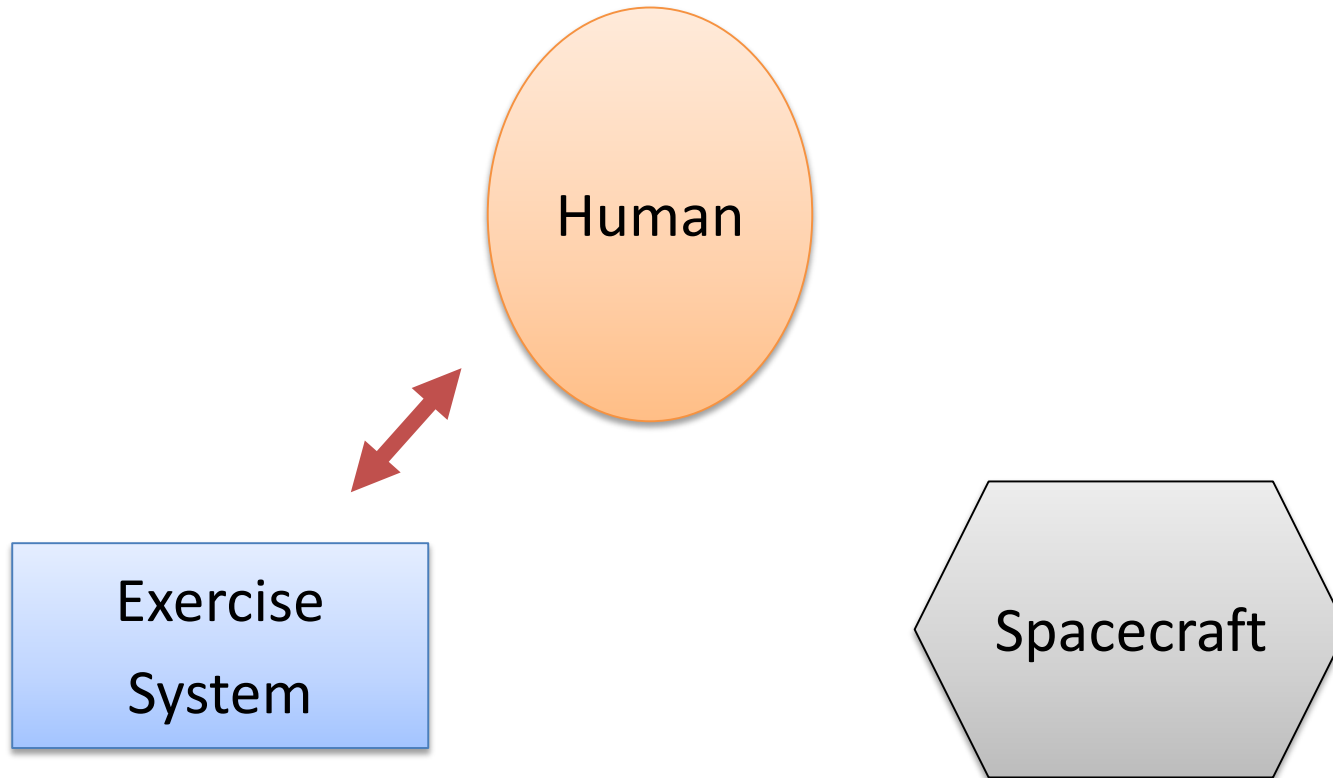
# **Digital Astronaut Simulation**

## **Experimental Study**

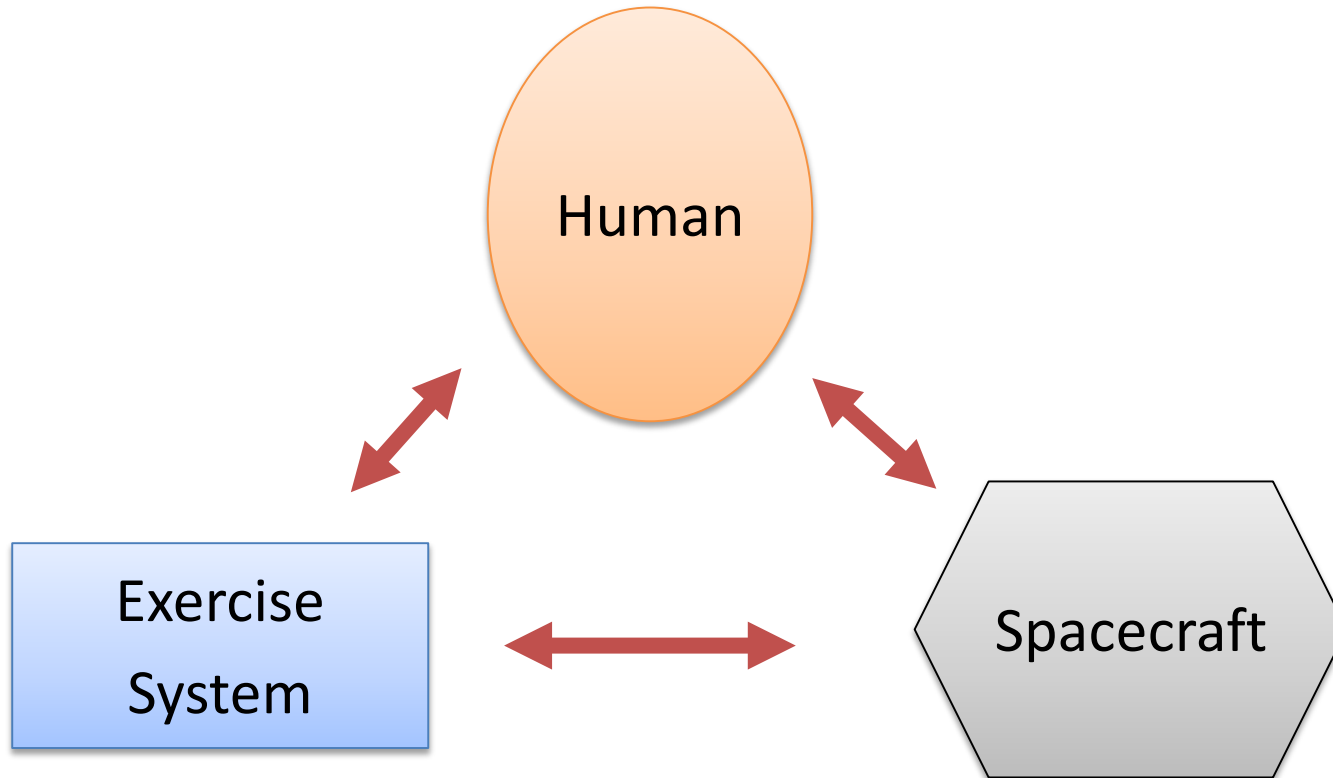
## **Results & Takeaways**

## **Next Steps**

# Digital Astronaut Simulation (DAS)

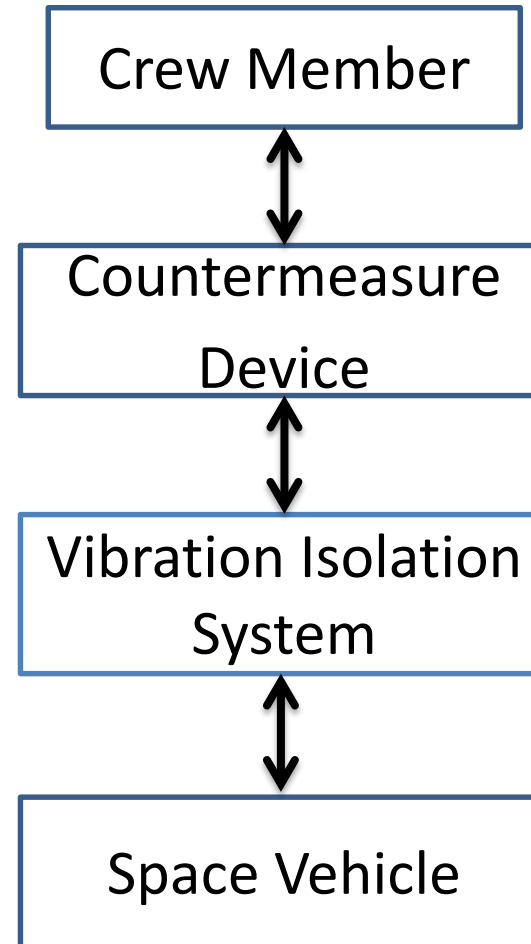
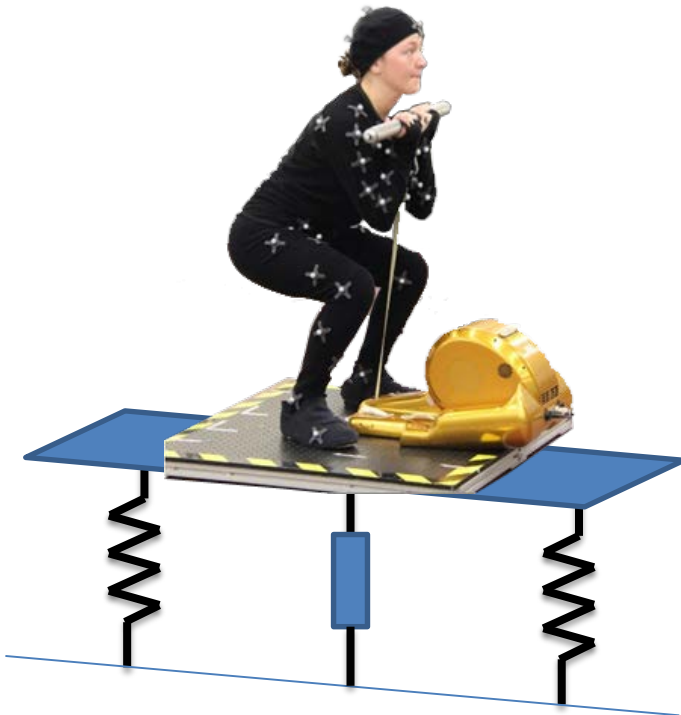


# Digital Astronaut Simulation (DAS)

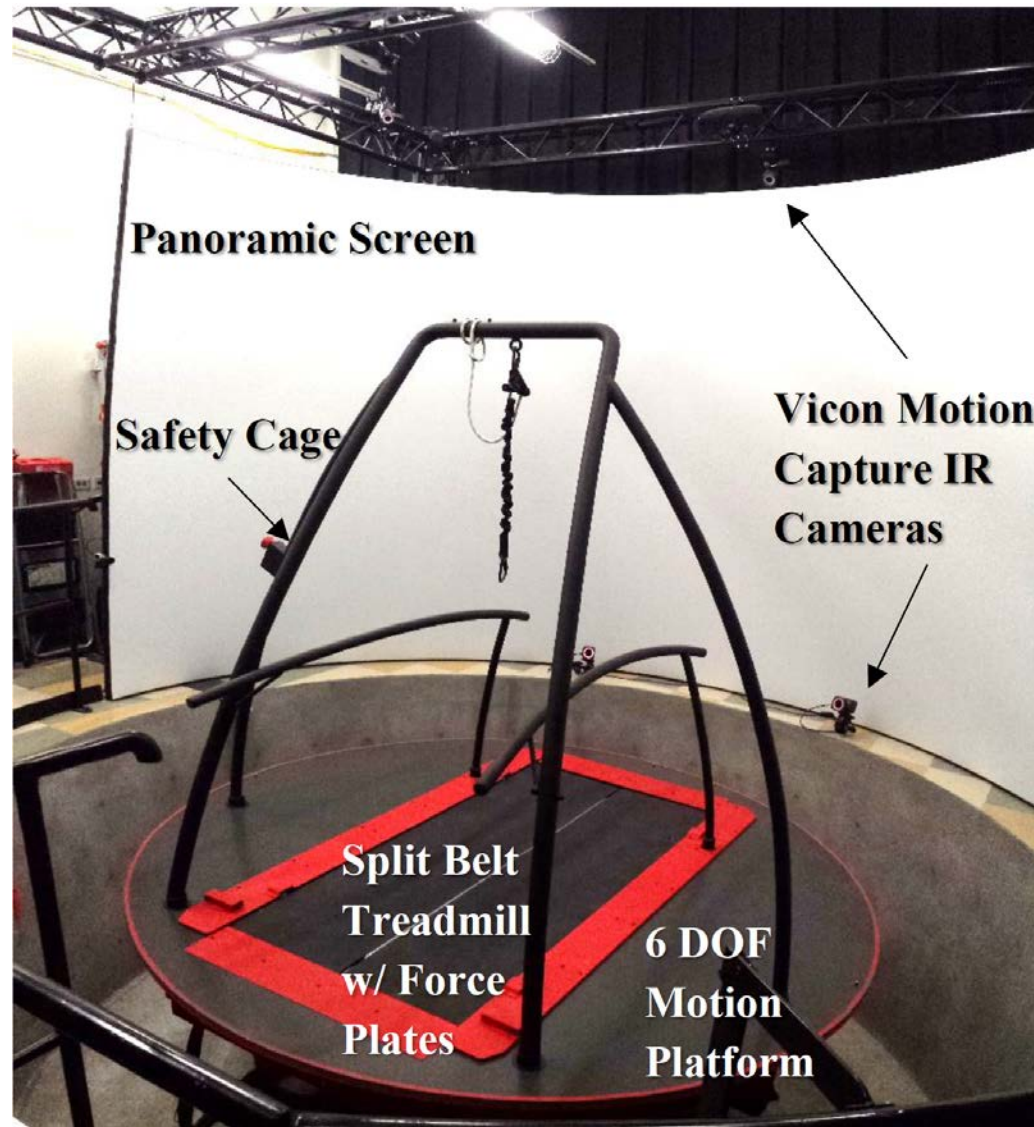





# Vibration Isolation System (VIS)



# Computer Assisted Rehabilitation Environment (CAREN) @ USF





A composite image of space scenes including a lunar surface, a small satellite, Mars, the Moon, and the International Space Station, all overlaid with a faint grid pattern.

# University Collaboration

## Digital Astronaut Simulation

# Experimental Study

## Results & Takeaways

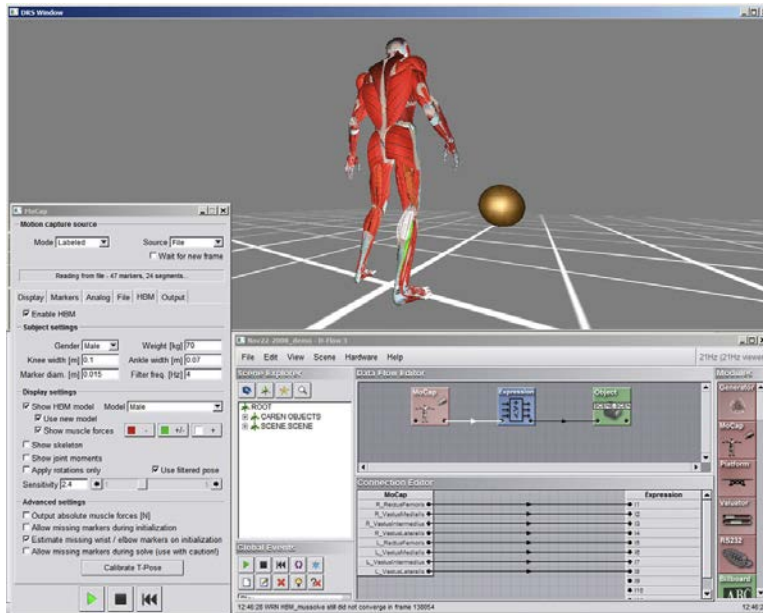
## Next Steps

# Computer Assisted Rehabilitation Environment (CAREN) @ USF



## Human Body Model

van den Bogert, A.J., Geijtenbeek, T., Even-Zohar, O. et al. A real-time system for biomechanical analysis of human movement and muscle function. Med Biol Eng Comput (2013) 51: 1069.

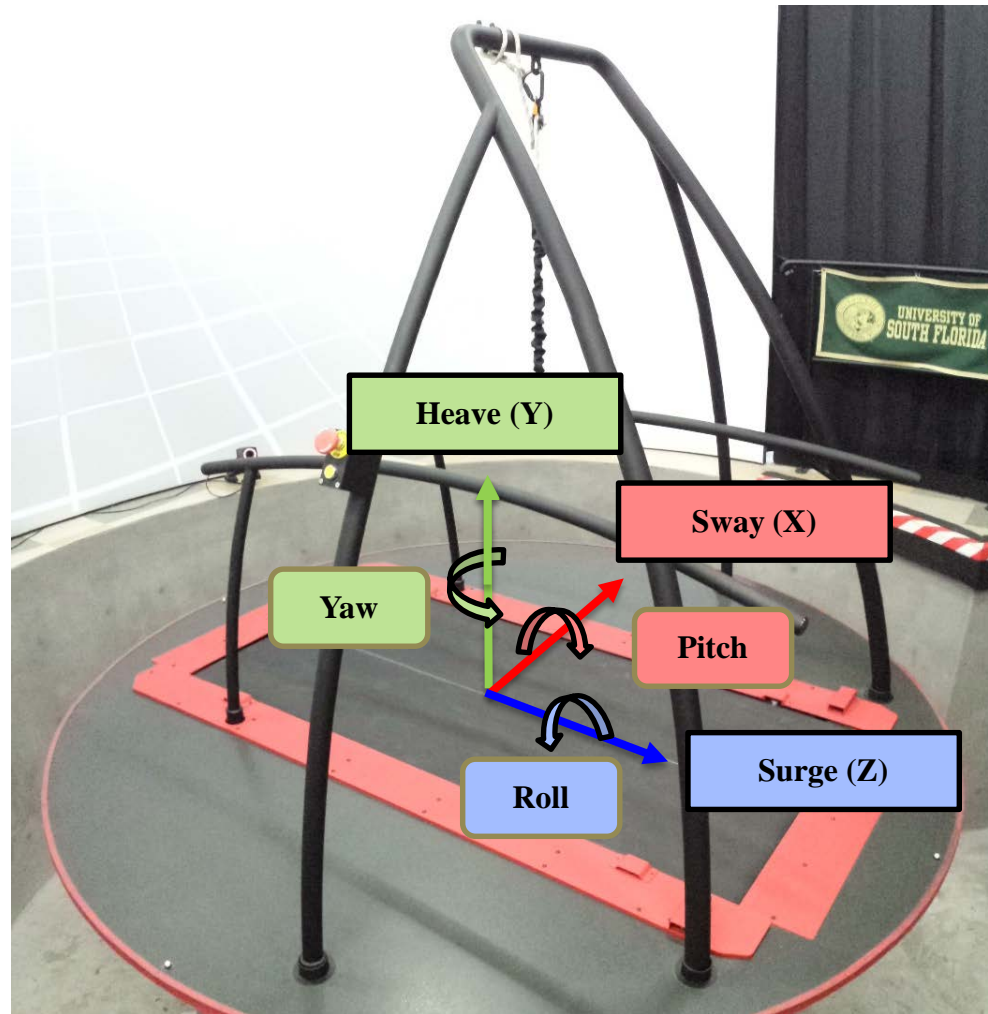


## Analog & Digital Signals

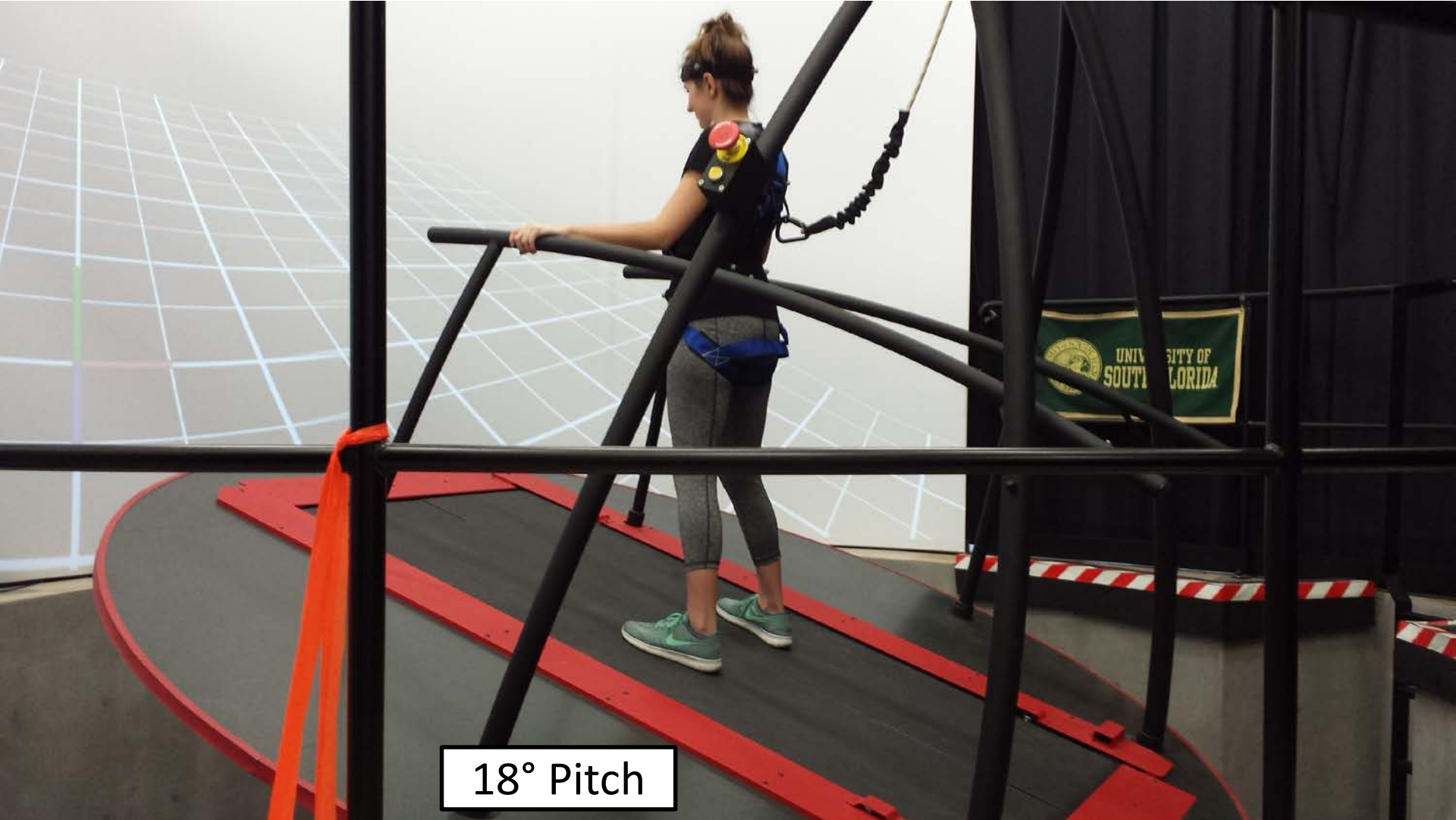




# Computer Assisted Rehabilitation Environment (CAREN) @ USF



# Computer Assisted Rehabilitation Environment (CAREN) @ USF



18° Pitch



# Specific Objectives



1. To develop proof-of-concept for ground based environment for human-in-the-loop testing of VIS dynamics
2. To study the effect of platform motion on human kinematic and kinetic response while completing resistive and aerobic exercise.

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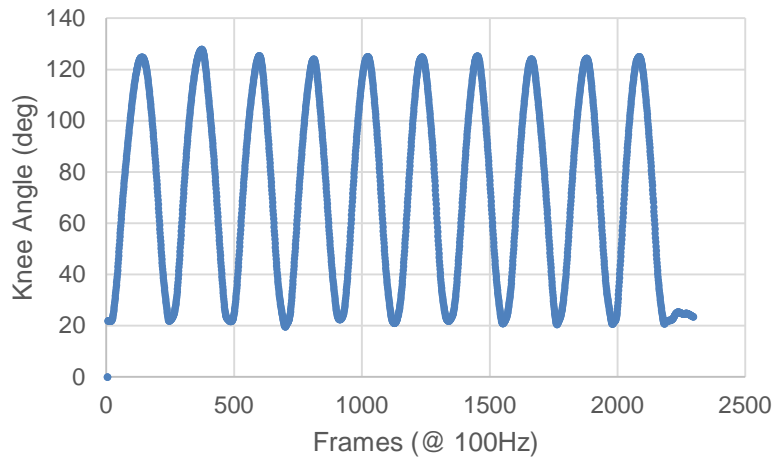
- DOFs of Interest:
  - 1 Translational
  - 1 Rotational
- Exercises of Interest:
  - Squats
  - Rowing
- Parameters of Interest:
  - Force
  - Motion



# Theory



Sample Squat Data

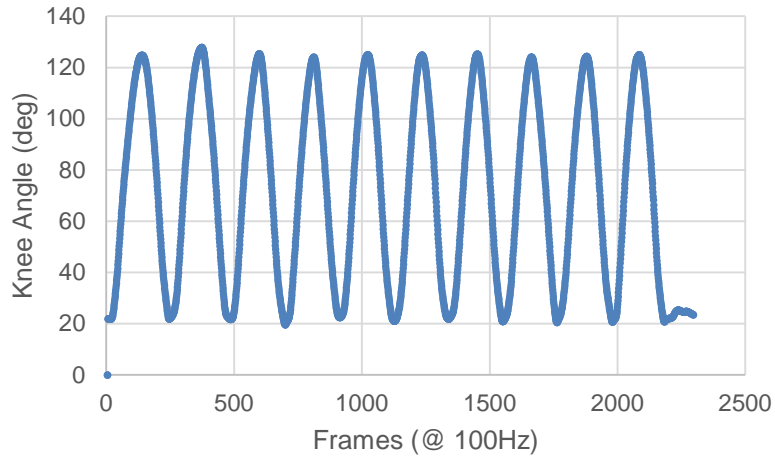


Bulk motion: Sinusoidal

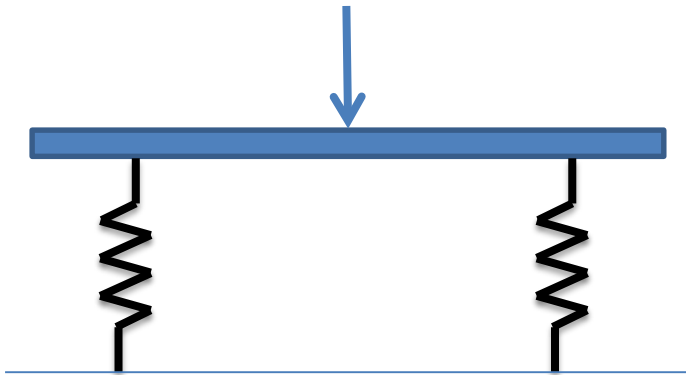
# Theory



Sample Squat Data

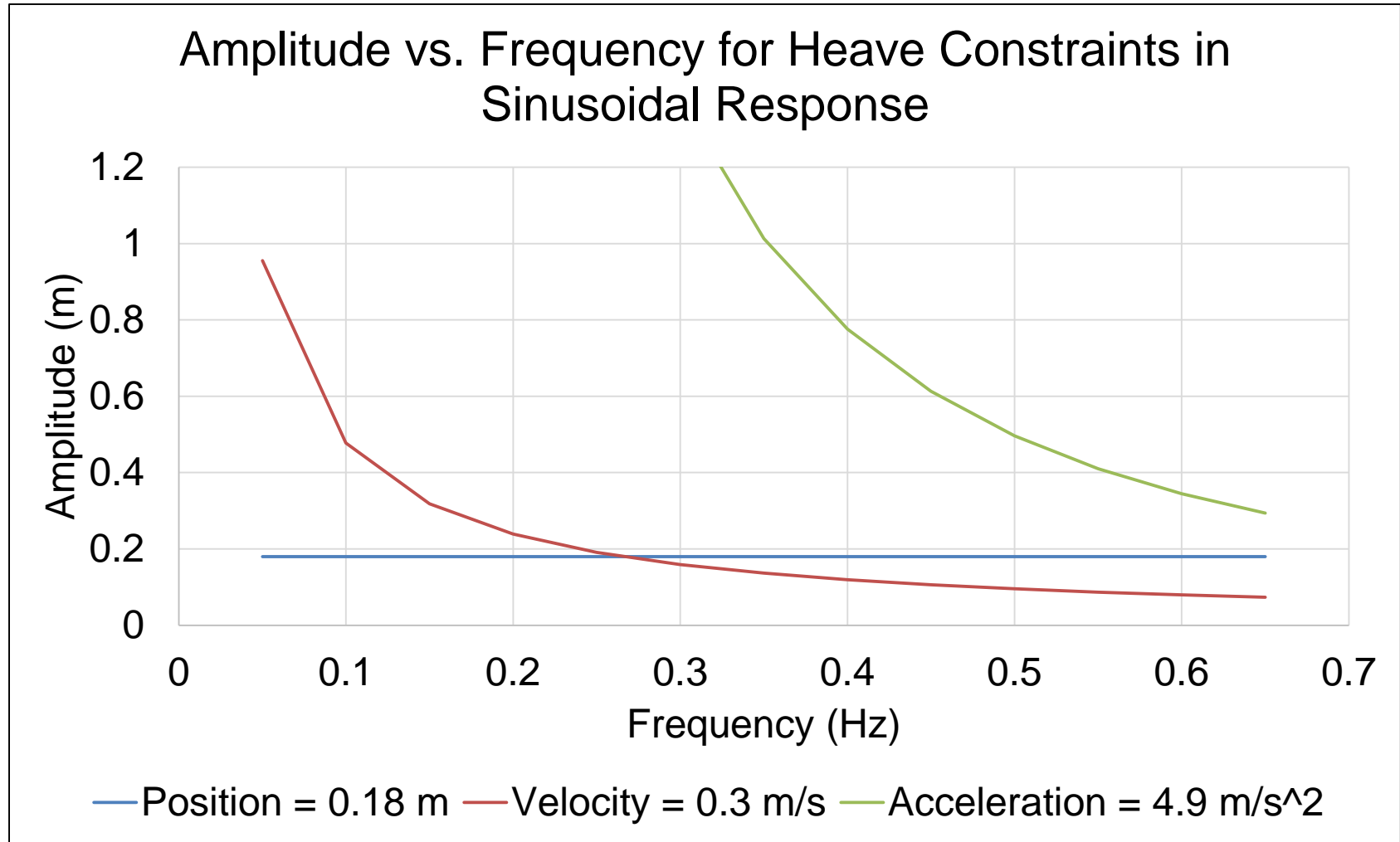


Bulk motion: Sinusoidal



Platform Dynamics:  
 $y(t) = A \sin(2\pi f t)$

# Constraint Determination





## Exercise & Platform Motion Frequencies

Frequencies Selected	Reason
0.10 Hz	ARED MILT & ISS Acceleration Environment
0.35 Hz	ARED MILT & midway point
0.60 Hz	ARED MILT & exercise point of interest
Self-selected	Nominal

**Participants instructed to match platform motion**

# Experimental Design



- **IRB Approved Human Subject Testing on CAREN**

## **System Components:**

- 2 DOF of motion platform

## **Instrumentation:**

- Motion Capture – Kinematics
- Force Plate Measurement – Kinetics

## **Environmental Distinctions:**

- 1G
- No external weight



# Experimental Method: Subjects



**N = 4**

Subject Designation	Gender	Age	Height (m)	Weight (lbs / N)
S1	Female	18	1.73	136.0 / 605.0
S2	Female	22	1.62	121.2 / 539.1
S3	Female	44	1.60	148.2 / 659.2
S4	Male	22	1.86	172.2 / 766.0

## Inclusion Criteria

1. Be between the ages of 18 and 65 years old
2. Have no physical impairments
3. Be able to complete exercise motions such as squats and vertical rows

## Participation

1 session, ~2 hours

# Experimental Method: Pre-Test Preparations



## Training

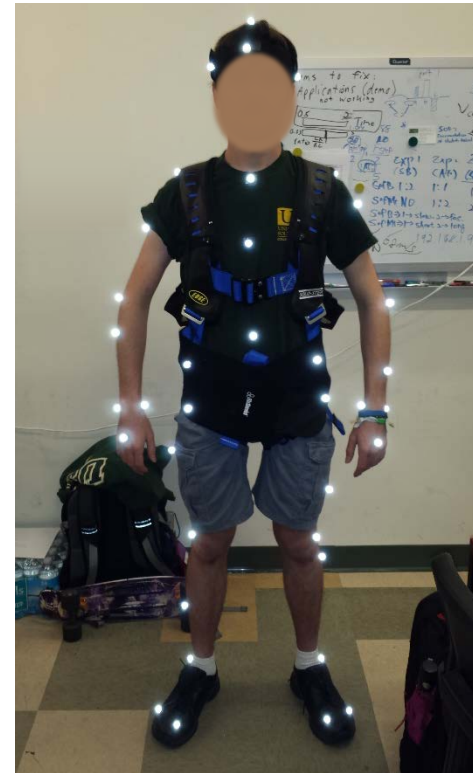
- Exercise Instruction
- Example Videos
- Instructed to match frequency of platform motion

## Measurements

- Height & Weight
- Individualized Subject Parameters

## Preparations

- Marker placement for motion capture



# Experimental Method: Trials



## Squat:

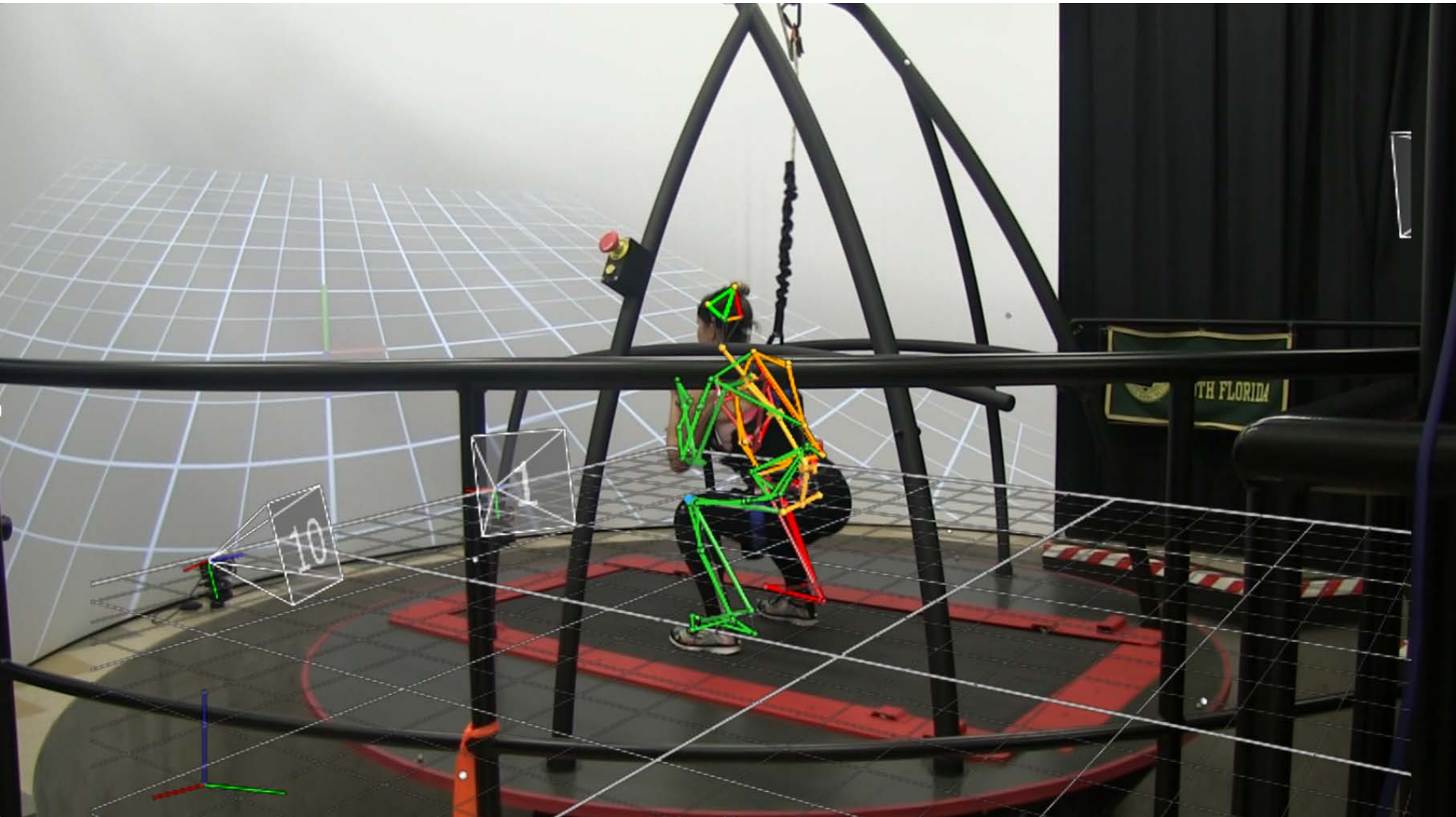
#	Exercise	Heave Frequency	Heave Amplitude	Pitch Freq	Pitch Amp
3	Baseline Squat	N/A (Static)	N/A (Static)	N/A	N/A
4	Squat	0.10 Hz	Baseline Measured	N/A	N/A
5	Squat	0.35 Hz	Baseline Measured	N/A	N/A
6	Squat	0.60 Hz	Baseline Measured	N/A	N/A
7	Squat	Baseline Measured Hz	Baseline Measured	N/A	N/A


## Row:

#	Exercise	Heave Frequency	Heave Amplitude	Pitch Freq	Pitch Amp
8	Baseline Row	N/A (Static)	N/A (Static)	N/A	N/A
9	Row	0.10 Hz	Baseline Measured	N/A	N/A
10	Row	0.35 Hz	Baseline Measured	N/A	N/A
11	Row	0.60 Hz	Baseline Measured	N/A	N/A
12	Row	Baseline Measured Hz	Baseline Measured	N/A	N/A
13	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	0.5 deg
14	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	1 deg
15	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	2 deg
16	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	3 deg



# Testing



The background of the slide is a composite image of space. On the left, a large, grey, cratered celestial body (likely an asteroid or part of a moon) is visible. In the center, a small satellite with a yellow antenna and solar panels is shown. To the right, a large, full moon is visible. In the bottom right corner, a portion of the Earth's blue and white horizon is shown, with a space station or large satellite structure orbiting above it. A faint grid pattern is overlaid on the entire background.

# **University Collaboration**

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# **Results & Takeaways**

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# Kinetic Data Processing

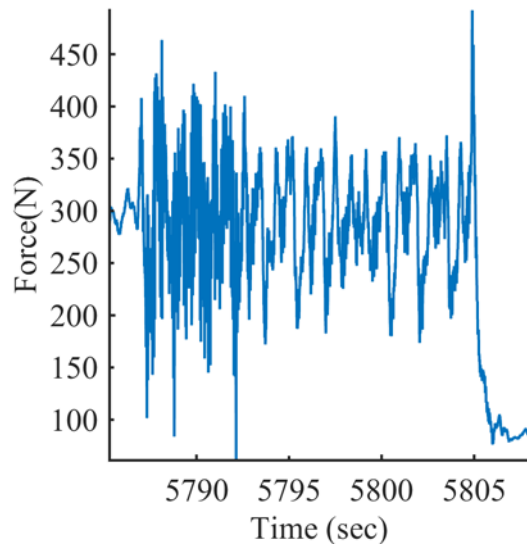


- **Data Extraction**

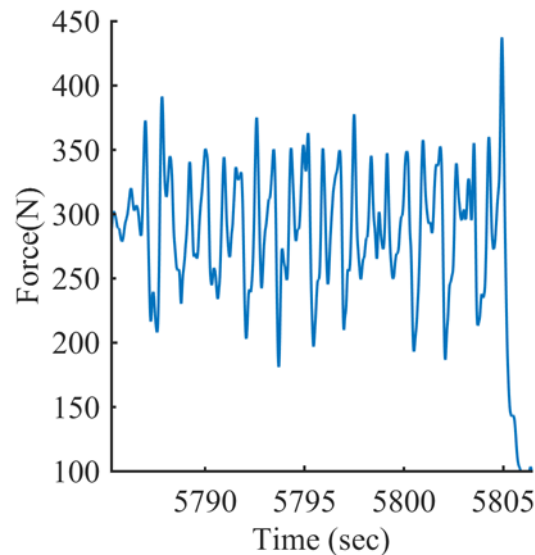
- **Filtering**

- **Computations**

- Resultant Force
- Average Maximum Force
- Average Force Range
- Force Frequency Matching



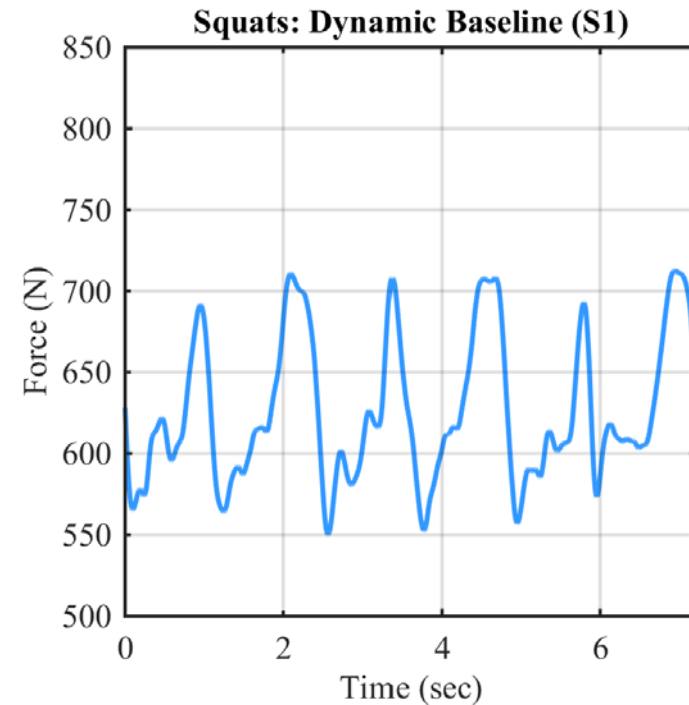
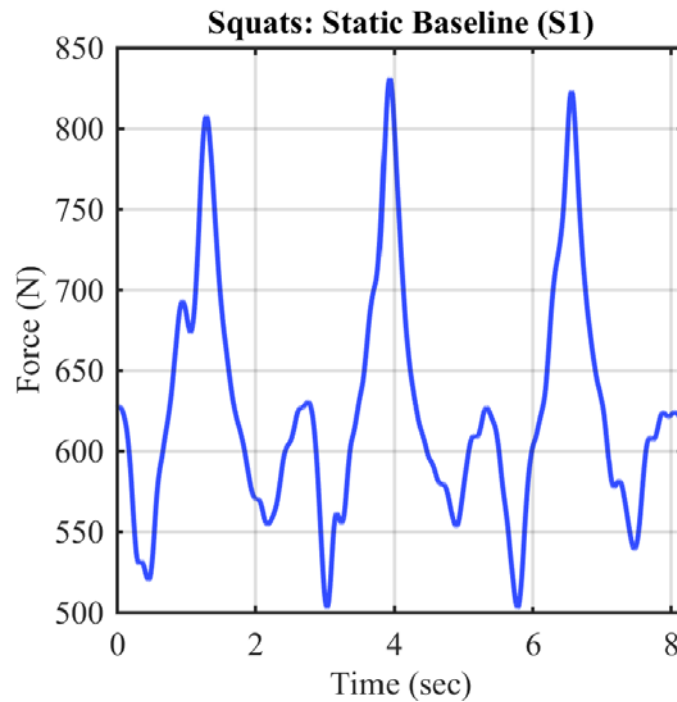
Unfiltered



Filtered



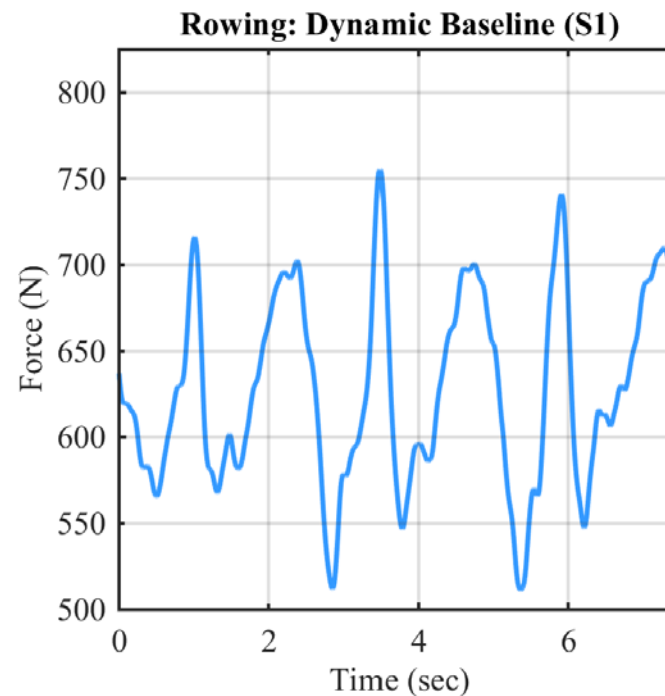
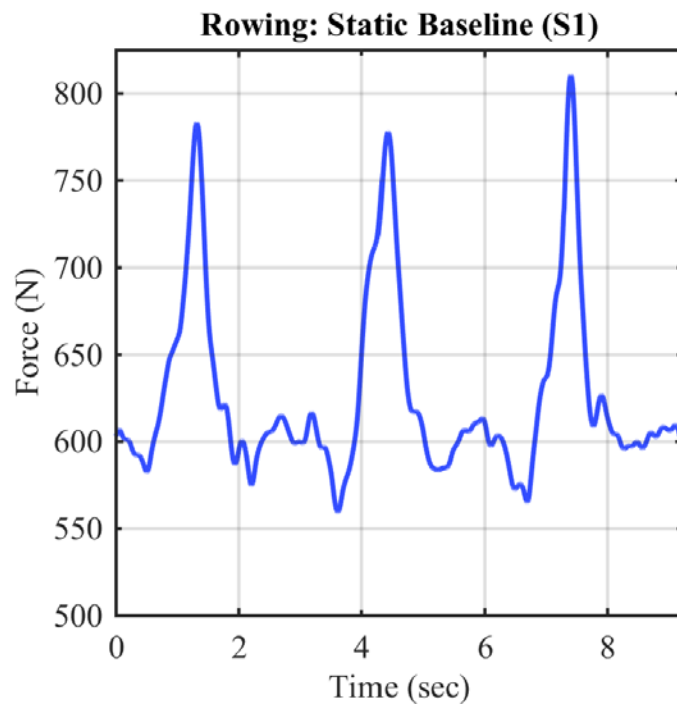
## Squats



# Kinetic Results: Ground Reaction Force Profiles



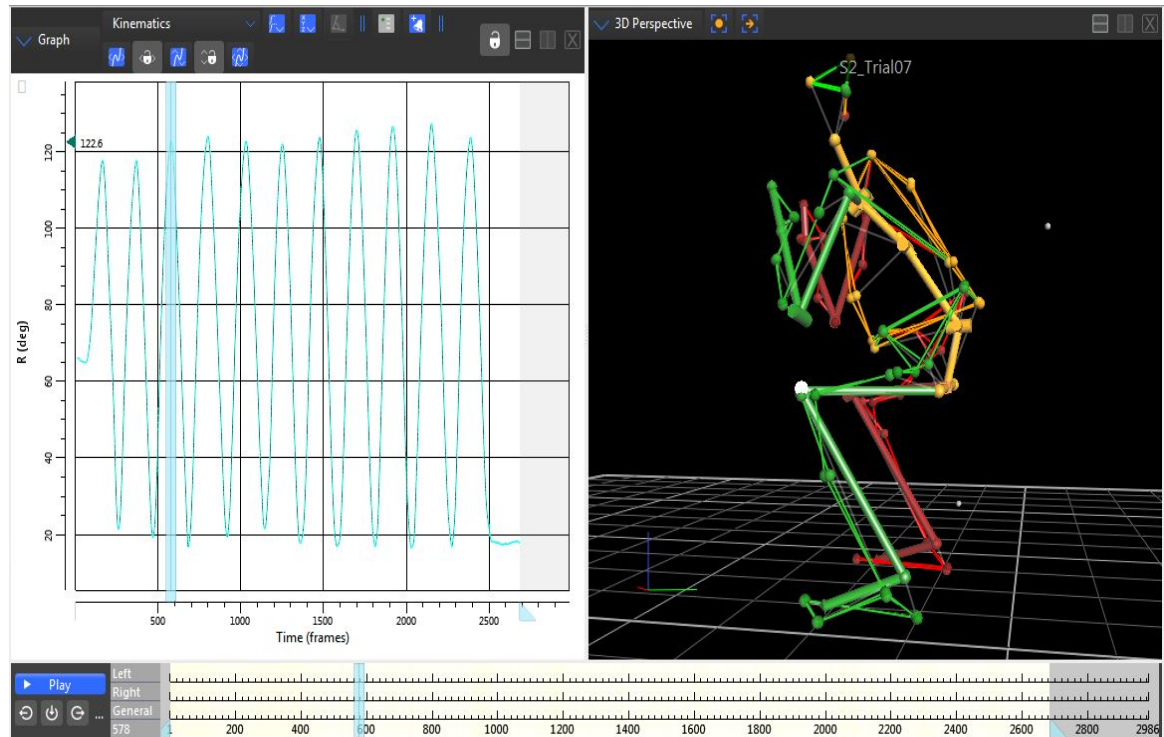
## Rows



# Kinematic Data Processing

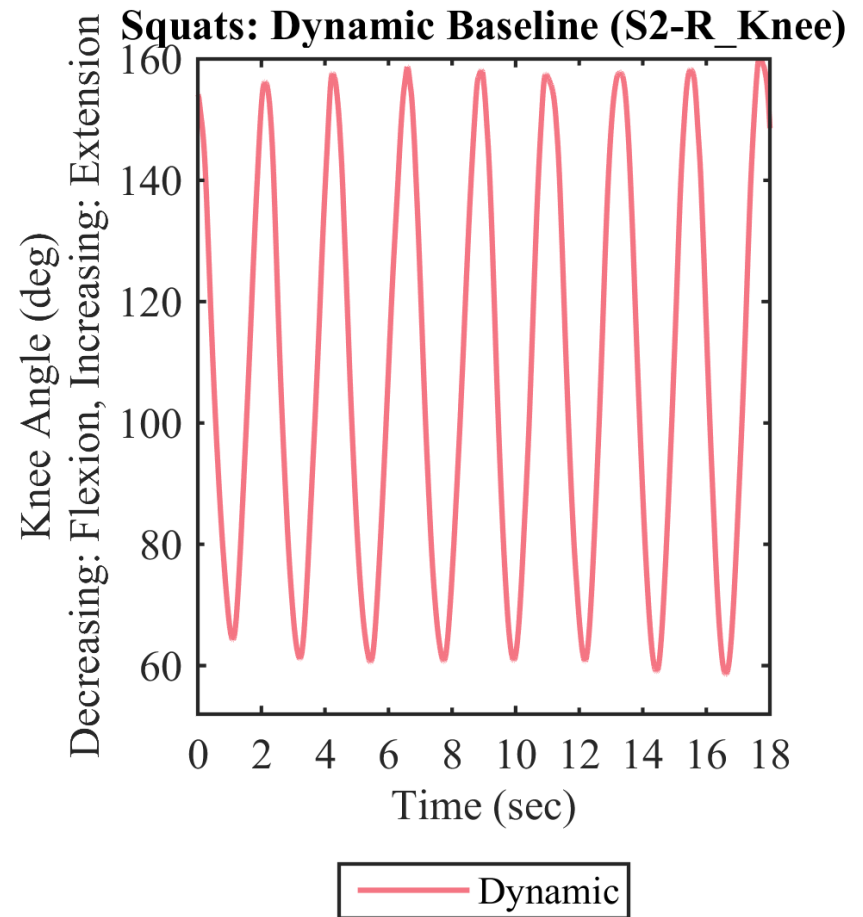
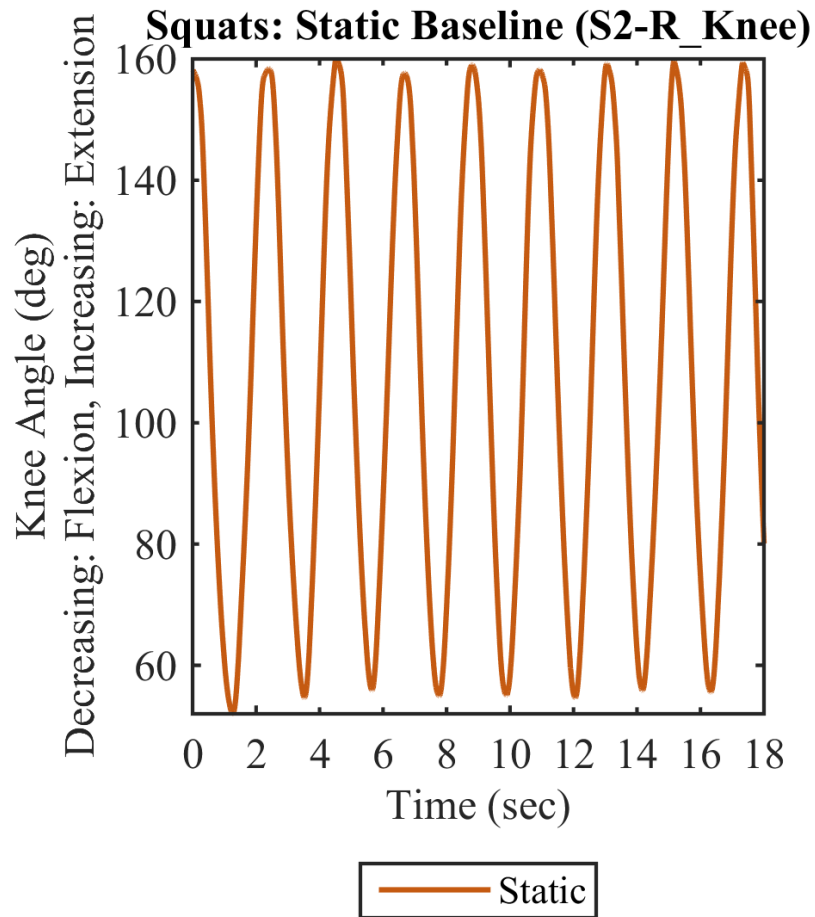



- **Data Cleaning**
- **Functional Skeletal Model**
  - Calculates Joint Center
  - Joint Angles
- **Computations**
  - Joint Angle ROM



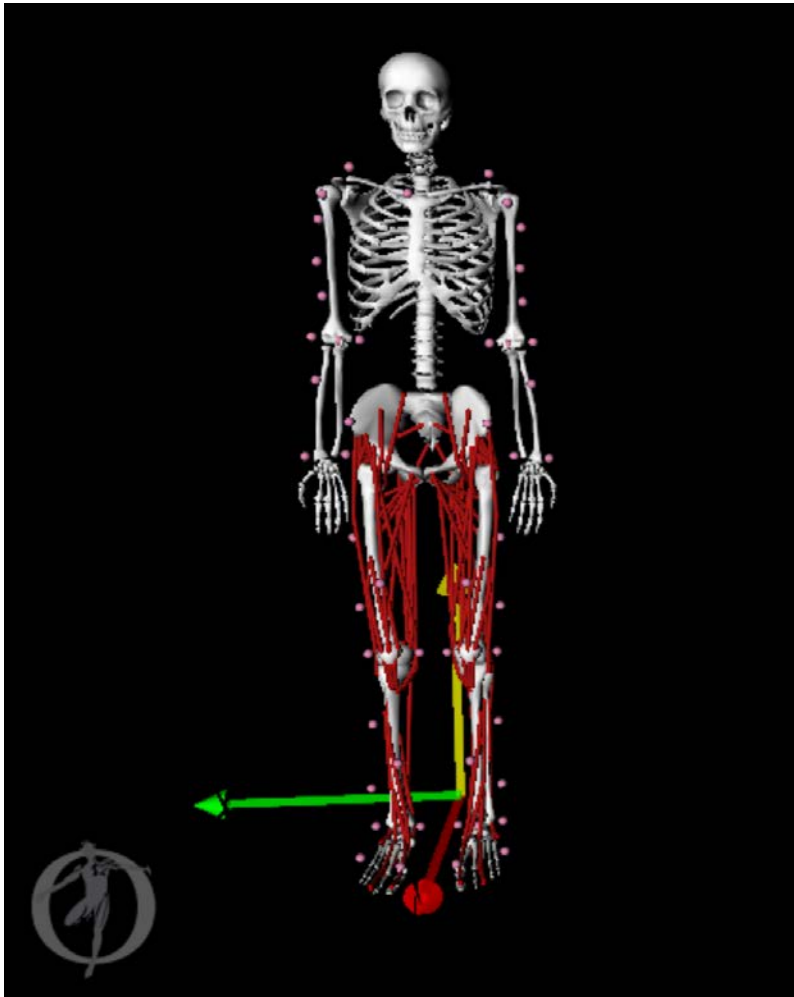


# Kinematic Results



A composite space-themed background featuring a grid overlay. It includes a close-up of a cratered celestial body on the left, a small satellite with yellow solar panels in the upper left, a reddish planet in the upper center, the full moon on the right, and the International Space Station in the lower right corner.

# **University Collaboration Digital Astronaut Simulation Experimental Study Results & Takeaways Next Steps**



**OpenSim, displaying:** Rajagopal, Apoorva, et al. "Full-Body Musculoskeletal Model for Muscle-Driven Simulation of Human Gait." IEEE Transactions on Biomedical Engineering 63.10 (2016): 2068-2079. (2016)

1. Scaling
2. Inverse Kinematics
3. Inverse Dynamics
4. Static Optimization

**OpenSim:** <http://opensim.stanford.edu/>

Seth, A., Hicks J.L., Uchida, T.K., Habib, A., Dembia, C.L., Dunne, J.J., Ong, C.F., DeMers, M.S., Rajagopal, A., Millard, M., Hamner, S.R., Arnold, E.M., Yong, J.R., Lakshmikanth, S.K., Sherman, n M.A., Delp, S.L. OpenSim: Simulating musculoskeletal dynamics and neuromuscular control to study human and animal movement. Plos Computational Biology, 14(7). (2018)

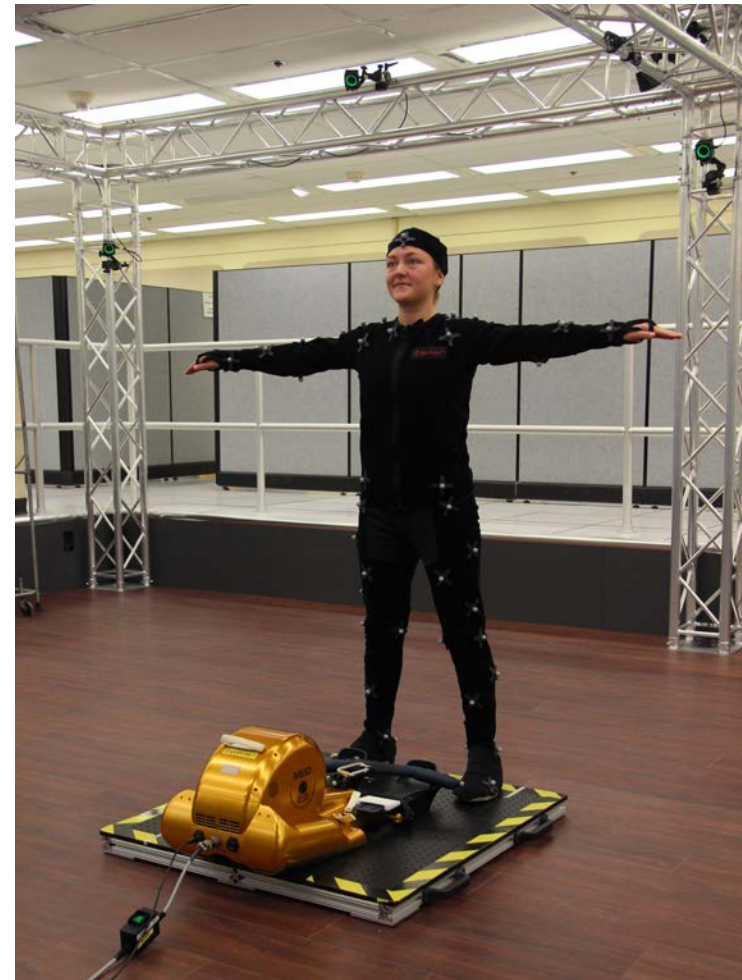
Delp, S.L., Anderson, F.C., Arnold, A.S., Loan, P., Habib, A., John, C.T., Guendelman, E., Thelan, D.G. OpenSim: Open-source software to create and analyze dynamic simulations of movement. IEEE Transactions on Biomedical Engineering , vol 55, pp 1940-1950. (2007)



# JSC Facilities



Active Response Gravity Offload System  
(ARGOS)



Prototype Immersive Technology Lab  
(PIT)

- **Enhancing CAREN as an analog for a passive VIS**
- **Development for active VIS**
- **PIT & ARGOS data collections**
- **VIS analyses and design using motion capture & force data from human-in-the-loop testing**
- **Incorporation of data feedback in exercise systems**

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**Johnson Space Center**

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**More information on this topic:**

Lostroscio, Kaitlin, "Developing Motion Platform Dynamics for Studying Biomechanical Responses During Exercise for Human Spaceflight Applications" (2018). Graduate Theses and Dissertations.

**<https://scholarcommons.usf.edu/etd/7191>**